

IN THE CLAIMS

Please amend the claims as follows:

1. (original) A system for manipulation of a small object comprising
 - a carrier to transport the small object
 - a substrate to receive the small object and
 - a fluid droplet which couples the small object detachably to the carrier and/or to the substrate.
2. (original) A system for manipulation of a small object as claimed in Claim 1 wherein
 - a carrying fluid droplet is disposed on the carrier.
3. (currently amended) A system for manipulation of a small object as claimed in Claim 1-~~or 2~~, wherein
 - a target fluid droplet is disposed in the substrate.
4. (original) A system for manipulation of a small object as claimed in Claim 1, wherein the target fluid droplet is placed on the substrate in predetermined positions or in a predetermined pattern.
5. (original) A system for manipulation of a small object as claimed in Claim 1, wherein the ratio of size of the fluid droplets to the size of the objects is in the range $^{1/10}$ to $^{1/3}$.
6. (original) A system for manipulation of a small object as claimed in Claim 1, wherein the substrate is provided with one or several electrodes.

7. (original) A system for manipulation of small objects as claimed in Claim 4 wherein the electrodes have a shape which corresponds to a shape of the small objects.

8. (original) A system for manipulation of a small object, comprising

- a pick-up plate on which pick-up carrying droplets are disposed
- a feeding plate on which feeder target droplets are disposed
- a placing plate on which several placing electrodes are disposed
- the feeding plate and the placing plate being coupled by a joint, in particular by a flexible joint and
- a device substrate on which substrate target droplets are disposed.

9. (original) A system for manipulation of a small object as claimed in Claim 6 being provided with

- a detection system responsive to the carrying fluid droplets on the pick-up plate to distinguish carrying fluid droplets carrying the small objects from empty fluid droplets and
- a droplet discard system responsive to the detection system to remove the empty fluid droplets from the pick-up plate.

10. (original) A method of manipulation of a small object having a carrying side with high wettability and a target side with low wettability

- placing said small object with its low wettability side on a carrying fluid droplet on a carrier
- bringing said carrier with the small object with its high wettability side into contact on deposition area on a substrate
- moving the carrier away from the substrate.

11. (original) A method as claimed in Claim 10, wherein with a target fluid droplet is placed at the deposition area.